

Comparing Two Systems Using Gaussian Copulae¹

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- Let $X = f_U(\mathbf{U}_X)$, $Y = g_U(\mathbf{U}_Y)$ where $\mathbf{U}_X, \mathbf{U}_Y \sim \mathcal{U}([0, 1]^d)$
- Standard sampling: \mathbf{U}_X is independent of \mathbf{U}_Y
- CRN sampling: $\mathbf{U}_X = \mathbf{U}_Y$
- $\text{var}(X - Y) = \text{var}X + \text{var}Y - 2\text{cov}(X, Y)$

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What is essential?

Let $\mathbf{U} = (\mathbf{U}_X, \mathbf{U}_Y)$

$$\mathbf{U} = (\underbrace{U_1, U_2, \dots, U_d}_{IID}, \underbrace{U_{d+1}, U_{d+2}, \dots, U_{2d}}_{IID})$$

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What is new ...

... is that we use a new class of copulas and have a computational method for searching over it

Let $\mathbf{Z} = (\mathbf{Z}_X, \mathbf{Z}_Y)$ be jointly Gaussian, standard normal marginals, covariance matrix

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$$X = f_U(\mathbf{U}_X) = f(\mathbf{Z}_X)$$

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Example 1

Take $d = 2$

$$X = f(\mathbf{Z}_X) = \frac{Z_X[1] + Z_X[2]}{\sqrt{2}}$$

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An optimal Gaussian copula:

$$\mathbf{Z}_Y[1] = \frac{Z_X[1] + Z_X[2]}{\sqrt{2}}$$

$$\mathbf{Z}_Y[2] = \frac{Z_X[1] - Z_X[2]}{\sqrt{2}}$$

so that $X = Y$ or, equivalently,

$$\Sigma_{XY} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

Example 2

Take $d = 1$

$$X = f_U(\mathbf{U}_X) = I(\mathbf{U}_X \in [0.5, 0.6])$$

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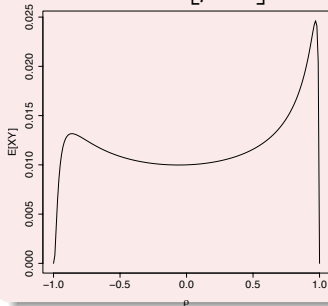
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Optimal Gaussian copula:

$$\text{var}(X - Y) = 0.15$$

$$\Sigma = \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix}$$



Optimizing the Copula

- $\min \text{var}(X - Y) \Leftrightarrow \max \text{cov}(X, Y) \Leftrightarrow \max Ef(\mathbf{Z}_X)g(\mathbf{Z}_Y)$

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subject to

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- Nonlinear semidefinite program
- Can be tackled, but gradients of objective are tricky
- Reformulate using Cholesky factors directly by observing that $\boldsymbol{\Sigma}_{XY}$ is “sub-orthogonal” ...

Proposition

$$\Sigma = \begin{bmatrix} I_d & \Sigma_{XY} \\ \Sigma_{XY}^T & I_d \end{bmatrix} \succeq 0 \iff \exists \mathbf{M}_2 : \mathbf{M}^T \mathbf{M} = I \text{ where } \mathbf{M} := \begin{bmatrix} \Sigma_{XY} \\ \mathbf{M}_2 \end{bmatrix}$$

Furthermore, Σ is covariance matrix of

$$\begin{bmatrix} \mathbf{Z}_X \\ \mathbf{Z}_Y \end{bmatrix} := \begin{bmatrix} \mathbf{N}[1, \dots, d] \\ \mathbf{M}^T \mathbf{N} \end{bmatrix}$$

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Notice that

$$\begin{bmatrix} I_d & 0_d \\ \Sigma_{XY}^T & \mathbf{M}_2^T \end{bmatrix} \begin{bmatrix} I_d & \Sigma_{XY} \\ 0_d & \mathbf{M}_2 \end{bmatrix} = \Sigma$$

Solving the Alternative Formulation

- $\max E f(\mathbf{Z}_X) g(\mathbf{M}^T \mathbf{N})$ subject to $\mathbf{M}^T \mathbf{M} = \mathbf{I}$
- Nonlinear optimization over a Stiefel manifold
- Gradients w.r.t. \mathbf{M} easily obtained

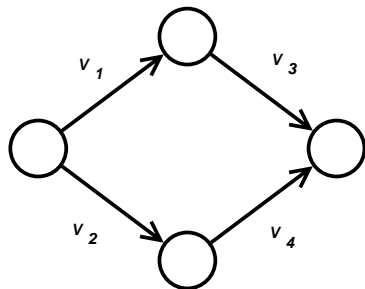
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- Use, e.g., sample-average approximation
- Sample and fix $\mathbf{N}_1, \dots, \mathbf{N}_m$, and

$$\begin{aligned} \max \quad & \frac{1}{m} \sum_{i=1}^m f(\mathbf{N}_i[1, \dots, d])g(\mathbf{M}^T \mathbf{N}_i) \\ \text{subject to} \quad & \mathbf{M}^T \mathbf{M} = \mathbf{I} \end{aligned}$$

- Freely available `sgmin` in MATLAB
- Use solution to above in subsequent conditionally independent simulation

Example 3



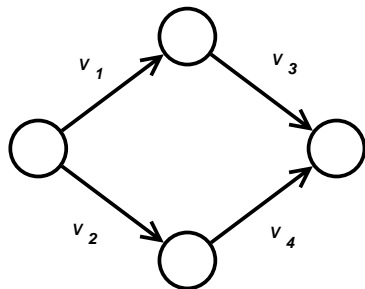
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$V_3 \sim \exp((1 + V_2)/2)$

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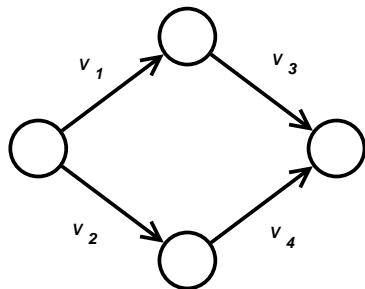
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Sampling Strategy	Variance
IID	5.3
CRN	0.57
OPT	0.28

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$\Sigma_{XY}^* =$

.958	-.038	.160	.237
-.037	.960	.239	.141
-.158	-.238	.957	-.048
-.239	-.143	-.026	.960

An Observation for Linear Functions

- The optimal Σ_{XY} in Example 1 was orthogonal
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Proposition

*If f and g are **linear**, then an optimal Σ_{XY} is orthogonal and corresponds to a Householder transformation that “aligns” the two linear functions.*

Conclusions and Future Research

- One might use more general joint distributions than CRN for comparisons
- Gaussian copula is particularly convenient
- Could use other copulas, e.g., chessboards, but computation needs to be feasible
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- One might use more general joint distributions than CRN for comparisons
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- Could use other copulas, e.g., chessboards, but computation needs to be feasible
- Simple examples demonstrate that large gains are possible
- When is optimization problem unimodal?
- Clarify connection to existing optimality results for CRN?
- More complicated (interesting?) examples?