Asymptotic Properties for Monte Carlo Methods

Kengo, KAMATANI

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# Asymptotic Properties for Monte Carlo Methods

#### Kengo, KAMATANI

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#### Introduction What is asymptotic?

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- This talk is concerned with asymptotic properties for the EM and the Gibbs.
- The meaning of asymptotic is that not only the number of iterations, but also the number of observations goes to infinity.

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• We address some asymptotic properties of the EM and the Gibbs.

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- We address some asymptotic properties of the EM and the Gibbs.
- Using this asymptotic properties, we validate some well known facts.

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- We address some asymptotic properties of the EM and the Gibbs.
  - Using this asymptotic properties, we validate some well known facts.
  - This type of arguments may be useful for constructing new Monte Carlo algorithms.

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#### We explain the motivation for the EM through an Example.

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- We explain the motivation for the EM through an Example.
- Let  $Y_{i,j}: \Omega \to \{0,1\}^2$   $(i = 1, \dots, n, j = 1, 2)$  be IID rv's such that

$$egin{aligned} & P_{ heta}(Y_{i,j}=(0,0))= heta_{0,0}, P_{ heta}(Y_{i,j}=(1,0))= heta_{1,0}, \ & P_{ heta}(Y_{i,j}=(0,1))= heta_{0,1}, P_{ heta}(Y_{i,j}=(1,1))= heta_{1,1}. \end{aligned}$$

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Assume that we do not observe (Y<sub>i,j</sub>), but (X<sub>i</sub> = Y<sub>i,1</sub> + Y<sub>i,2</sub>).

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• Let  $Y_i = \{Y_{i,1}, Y_{i,2}\}$ . Consider four observations.

$$\begin{array}{ll} Y_1 = \{(0,0),(0,0)\}, & Y_2 = \{(1,1),(0,0)\}\\ Y_3 = \{(1,1),(1,0)\}, & Y_4 = \{(0,1),(1,0)\} \end{array}$$

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Then,

$$egin{aligned} X_1 &= (0,0), & X_2 &= (1,1) \ X_3 &= (2,1), & X_4 &= (1,1) \end{aligned}$$

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Then,

• Let  $T_{a,b}$  denote  $\sum_{i,j} 1_{\{Y_{i,j}=(a,b)\}}$  (a, b = 0, 1). That is  $T_{0,0} = 3, T_{0,1} = 1, T_{1,0} = 2, T_{1,1} = 2$ .

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#### E-Step: Calculate $Q(\theta^{i-1}, \vartheta) = 2 \sum_{a,b=0,1} \log \vartheta_{a,b} \mathbf{E}_{\theta^{i-1}}[T_{a,b}|X_1, \dots, X_n]$ M-Step: Set $\theta^i = \arg \max_{\vartheta} Q(\theta^{i-1}, \vartheta)$ .

The M-step is,

$$\theta_{a,b}^i = \mathbf{E}_{\theta^{i-1}}[\frac{T_{a,b}}{2n}|X_1,\ldots,X_n].$$

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• This EM algorithm works well when we take a good initial point  $\theta^0$ .

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- This EM algorithm works well when we take a good initial point  $\theta^0$ .
- Does the sequence converge to MLE  $\hat{\theta}_n$ ?

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- This EM algorithm works well when we take a good initial point  $\theta^0$ .
- Does the sequence converge to MLE  $\hat{\theta}_n$ ?
- Computer simulation tells us good information. But, how about theoretical validation?

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We have,

$$\frac{1}{n}\partial_{\theta}\log L_n(\theta^{i-1}) = I_{1,2}(\theta^{i-1})(\theta^i - \theta^{i-1}),$$

where  $L_n(\theta)$  is the likelihood and  $I_{1,2}(\theta)$  is the Fisher information of (X, Y).

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where  $L_n(\theta)$  is the likelihood and  $I_{1,2}(\theta)$  is the Fisher information of (X, Y).

Under some regularity conditions,

$$\frac{1}{n}(\partial_{\theta} \log L_n(\theta^{i-1}) - \partial_{\theta} \log L_n(\hat{\theta}_n)) \sim -I(\theta^{i-1})(\theta^{i-1} - \hat{\theta}_n).$$

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Under some regularity conditions,

$$\frac{1}{n}(\partial_{\theta} \log L_n(\theta^{i-1}) - \partial_{\theta} \log L_n(\hat{\theta}_n)) \sim -I(\theta^{i-1})(\theta^{i-1} - \hat{\theta}_n).$$

■ Therefore, by easy calculation,

$$\theta^{i} - \hat{\theta}_{n} \sim J(\theta^{i-1})(\theta^{i-1} - \hat{\theta}_{n}),$$

where  $J(\theta) = I - I_{1,2}(\theta)^{-1}I(\theta_0)$ .

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Under some regularity conditions, we have

$$(\theta^i - \hat{\theta}_n) \sim J(\hat{\theta}_n)^i (\theta^0 - \hat{\theta}_n) \sim 0.$$

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Under some regularity conditions, we have

$$( heta^i - \hat{ heta}_n) \sim J(\hat{ heta}_n)^i ( heta^0 - \hat{ heta}_n) \sim 0.$$

A similar expansion as above is well known.

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Under some regularity conditions, we have

$$(\theta^i - \hat{\theta}_n) \sim J(\hat{\theta}_n)^i (\theta^0 - \hat{\theta}_n) \sim 0.$$

- A similar expansion as above is well known.
- We want to know what is the regularity condition. I tried to find any paper related to the validation of the above expansion.

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■ Under some regularity conditions, we have

$$( heta^i - \hat{ heta}_n) \sim J(\hat{ heta}_n)^i ( heta^0 - \hat{ heta}_n) \sim 0.$$

- A similar expansion as above is well known.
- We want to know what is the regularity condition. I tried to find any paper related to the validation of the above expansion.
- Surprisingly, I could not find any validation for the above expansion!

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Under some regularity conditions, we have

$$( heta^i - \hat{ heta}_n) \sim J(\hat{ heta}_n)^i ( heta^0 - \hat{ heta}_n) \sim 0.$$

- A similar expansion as above is well known.
- We want to know what is the regularity condition. I tried to find any paper related to the validation of the above expansion.
- Surprisingly, I could not find any validation for the above expansion!
- So we address the validity issue.

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We can show that the sequence of the EM algorithm converges to the MLE. It is difficult under small sample framework.

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- We can show that the sequence of the EM algorithm converges to the MLE. It is difficult under small sample framework.
- The rate matrix determines the convergence rate. This fact is validated under large sample statistical theory.

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onclusion

- We can show that the sequence of the EM algorithm converges to the MLE. It is difficult under small sample framework.
- The rate matrix determines the convergence rate. This fact is validated under large sample statistical theory.
- It may be useful for other complicated algorithms.

#### Some drawbacks for large sample properties

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• We assume a large sample size. Sometimes it is difficult to assume.

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- We assume a large sample size. Sometimes it is difficult to assume.
- We assume that the initial point θ<sup>0</sup> is in a neighborhood of the true value θ<sub>0</sub>. (A kind of moment estimator works well.)

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Conclusion

• Let  $\theta_0$  be a true parameter. Then, under general assumptions,

$$\log L_{h,n} = \langle h, Z_n 
angle - rac{1}{2} \langle h, I( heta_0)h 
angle + o_{\mathcal{P}_{ heta_0}^n}(1),$$

where  $\log L_{h,n} = \sum \log p_{\theta_0 + hn^{-1/2}}(x_i)/p_{\theta_0}(x_i)$  and  $Z_n = n^{-1/2} \sum \partial \log p_{\theta_0}(x_i)$ .

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$$\log L_{h,n} = \langle h, Z_n 
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angle + o_{\mathcal{P}_{ heta_0}^n}(1),$$

where 
$$\log L_{h,n} = \sum \log p_{\theta_0 + hn^{-1/2}}(x_i)/p_{\theta_0}(x_i)$$
 and  $Z_n = n^{-1/2} \sum \partial \log p_{\theta_0}(x_i)$ .

• The right hand side is maximized at  $h = I(\theta_0)^{-1}Z_n$ .

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• Let  $\theta_0$  be a true parameter. Then, under general assumptions,

$$\log L_{h,n} = \langle h, Z_n 
angle - rac{1}{2} \langle h, I( heta_0)h 
angle + o_{\mathcal{P}_{ heta_0}^n}(1),$$

where 
$$\log L_{h,n} = \sum \log p_{\theta_0 + hn^{-1/2}}(x_i)/p_{\theta_0}(x_i)$$
 and  
 $Z_n = n^{-1/2} \sum \partial \log p_{\theta_0}(x_i).$ 

- The right hand side is maximized at  $h = I(\theta_0)^{-1} Z_n$ .
- Using this expansion, under some regularity condition, we have

$$n^{1/2}(\hat{\theta}_n-\theta_0)\Rightarrow N(0,I(\theta_0)^{-1}).$$

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• We take two parametric families  

$$(\mathcal{X}, \mathcal{A}, P_{\theta}(dx) = p_{\theta}(x)dx; \theta \in \Theta)$$
 and  
 $(\mathcal{Y}, \mathcal{B}, P_{x,\theta}^{2|1}(dy) = p_{x,\theta}^{2|1}(y)dy; \theta \in \Theta, x \in \mathcal{X}).$ 

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• We take two parametric families  

$$(\mathcal{X}, \mathcal{A}, P_{\theta}(dx) = p_{\theta}(x)dx; \theta \in \Theta) \text{ and}$$

$$(\mathcal{Y}, \mathcal{B}, P_{x,\theta}^{2|1}(dy) = p_{x,\theta}^{2|1}(y)dy; \theta \in \Theta, x \in \mathcal{X}).$$
• Let  $p_s^{1,2}(x, y) = p_s(x)p_{x,s}^{2|1}(y).$   
• Let  

$$Q_{s,t}(x) = \int_{\mathcal{Y}} \log \frac{p_t^{1,2}(x, y)}{p_s^{1,2}(x, y)} dP_{x,s}^{2|1}(dy)$$

and

$$Q_{s,t,n}(x^{(n)}) = \sum_{i=1}^{n} Q_{\theta_0 + sn^{-1/2}, \theta_0 + tn^{-1/2}}(x_i).$$

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• Under some regularity conditions,  $Q_{s,t,n}(x^{(n)}) = \overline{Q}_{s,t,n}(x^{(n)}) + o_{P^n_{\theta_0}}(1)$ , where  $\overline{Q}_{s,t,n}$  is

$$-\frac{1}{2}\langle t, I_{1,2}(\theta_0)t\rangle + \langle t, Z_n + (I_{1,2}(\theta_0) - I(\theta_0))s\rangle + c_n(s, \theta_0, x^{(n)})$$

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$$-\frac{1}{2}\langle t, I_{1,2}(\theta_0)t\rangle + \langle t, Z_n + (I_{1,2}(\theta_0) - I(\theta_0))s\rangle + c_n(s, \theta_0, x^{(n)})$$

Note that, the maximizer of  $\overline{Q}_{s,t,n}$  with respect to t satisfies

$$t-\mu_n=J(\theta_0)(s-\mu_n),$$

where  $\mu_n = I(\theta_0)^{-1} Z_n$ .

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#### The Result

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Theorem (Convergence Theorem for the EM)

Under some regularity conditions, for any  $m_n \rightarrow \infty$ ,

$$n^{1/2}( heta^{m_n}-\hat{ heta}_n)=o_{\mathcal{P}_{ heta_0}^n}(1),$$

where  $\theta^0, \theta^1, \ldots$  is the sequence of the EM algorithm.

In the above result, we assume that for  $\theta^0 = \theta_n^0$ , for any  $\epsilon > 0$ , there exists  $\delta > 0$  such that

$$\limsup_{n \to \infty} P^n_{\theta_0}(n^{1/2}|\theta^0_n - \theta_0| > \delta) \le \epsilon.$$
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# **Regularity Condition**

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#### Assumption (Smoothness Assumption for the EM)

There exist some  $\epsilon > 0$ , and some  $M \in L^2(P_{\theta_0})$  such that for any  $s, t, u, v \in B_{\epsilon}(\theta_0)$ , we have

$$|Q_{s,u}(x) - Q_{t,v}(x)| \le M(x)(|s-t|^2 + |u-v|^2)^{1/2}.$$

# • The Fisher information matrix $I(\theta)$ is continuous around $\theta_0$ .

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• We explain the motivation for the Gibbs through the Example, which is used in the previous section.

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- We explain the motivation for the Gibbs through the Example, which is used in the previous section.
- The prior distribution is  $Dir(\alpha)$ , where  $\alpha = (\alpha_{0.0}, \alpha_{0.1}, \alpha_{1.0}, \alpha_{1.1})$ .

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# Step i: For j = 1, ..., n, generate $y_{i,j} = (y_{i,j,1}, y_{i,j,2})$ from $P_{\theta^{i-1}}^{2|1}(dy_{i,j}|x_j)$ . Then calculate $T_{a,b,n}^i = \sum_{j=1}^n T_{a,b}(y_{i,j,1}, y_{i,j,2})$ and set $T_n^i = (T_{0,0,n}^i, T_{0,1,n}^i, T_{1,0,n}^i, T_{1,1,n}^i)$ . Generate $\theta^i$ from $\text{Dir}(\alpha + T_n^i)$ .

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The above procedure defines a Markov transition kernel  $F_{x^{(n)},\theta,n}(d\varphi) = f_{x^{(n)},\theta,n}(\varphi)d\varphi$ . We have

$$f_{x^{(n)},\theta,n}(\varphi) \geq \frac{\Gamma(2n+\sum_{a,b=0}^{1}\alpha_{a,b})}{\prod_{a,b=0}^{1}\Gamma(2n+\alpha_{a,b})}\prod_{a,b=0}^{1}\varphi_{a,b}^{2n+\alpha_{a,b}-1},$$

Moreover, we have

$$\|F_{x^{(n)},n} - F_{x^{(n)},\theta,n}^m\|_{\mathrm{TV}} \le \rho^m$$

where  $F_{x^{(n)},n}$  is the posterior, and  $\rho = 1 - \Gamma(2n + \sum_{a,b=0}^{1} \alpha_{a,b}) / \Gamma(8n + \sum_{a,b=0}^{1} \alpha_{a,b})$ 

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We approximate the Gibbs sampler by a simple transition kernel, which is defined by simple statistics.

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- We approximate the Gibbs sampler by a simple transition kernel, which is defined by simple statistics.
- Therefore, we can measure the convergence rate of the Gibbs sampler by the simple statistics.

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- We approximate the Gibbs sampler by a simple transition kernel, which is defined by simple statistics.
- Therefore, we can measure the convergence rate of the Gibbs sampler by the simple statistics.
- In some situation, it is reasonable to consider large sample theory.

#### Some drawbacks for large sample properties

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• We assume a large sample. Sometimes it is difficult to assume.

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- We assume a large sample. Sometimes it is difficult to assume.
- We assume that the initial guess θ<sup>0</sup> is in a neighborhood of the true value θ<sub>0</sub>. A kind of moment estimator works well.

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## Asymptotic Theory for the Gibbs sampler

Asymptotic Properties for Monte Carlo Methods • We showed that the sequence of the Gibbs sampler tends to the following Markov chain: Asymptotic Theory

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#### Asymptotic Theory for the Gibbs sampler

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- We showed that the sequence of the Gibbs sampler tends to the following Markov chain:
- The Markov chain  $h_1, h_2, \ldots$  satisfies

$$h_i - \mu_n = J(\theta_0)(h_{i-1} - \mu_n) + \epsilon_i$$

where  $\epsilon_i = N(0, 2I_{1,2}(\theta_0)^{-1} - I_{1,2}(\theta_0)^{-1}I(\theta_0)I_{1,2}(\theta_0)^{-1}).$ 

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Theorem (Convergence Theorem for the Gibbs)

Under some regularity conditions, we have

$$n^{1/2}| ilde{ heta}^{I_n}- ilde{ heta}_n|=o_{P^n_{ heta_0}}(1),$$

Note that  $\tilde{\theta}^{l_n}$  is the empirical median of the sequence of the Gibbs sampler such that  $\theta^0 = \theta_n^0 \sim \nu_{\chi^{(n)},n}$ . We assume that for any  $\epsilon > 0$ , there exists  $\delta > 0$ ,

$$\limsup_{n \to \infty} P^n_{\theta_0}(n^{1/2}|\theta^0_n - \theta_0| > \delta) \le \epsilon.$$
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#### Regularity Condition Smoothness of the model

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#### Assumption (Smoothness Assumption for the Gibbs)

For some  $\epsilon > 0$ , there exists a constant C > 0 and for any  $s, t \in B_{\epsilon}(\theta_0)$ , we have

$$H(P_{x,s}^{2|1}, P_{x,t}^{2|1}) \le M(x)|s-t|$$

where  $M(x) \in L^2(P_{\theta_0})$ .

• The Fisher information matrix  $I(\theta)$  is continuous around  $\theta_0$ .

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#### Regularity Condition Existence of uniformly consistent test

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#### Assumption (Existence of Uniformly Consistent Test)

There exists an integer N and a test  $\omega_n = \omega_n(x_1, \ldots, x_n)$  on  $(\mathcal{X}^n, \mathcal{A}^n)$ , such that there exists a constant  $\epsilon_0 \in (0, 1/2)$  and a compact subset K of  $\Theta$  such that

$$P_{ heta_0}^{(n)}(\omega_n) \leq \epsilon_0, P_{ heta}^{(n)}(1-\omega_n) \leq \epsilon_0 \; (orall heta \in K^c).$$

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 We showed convergence theorems for the EM and the Gibbs.

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- We showed convergence theorems for the EM and the Gibbs.
- These two algorithms are approximated by simple algorithms. Using this approximation, we can compare different algorithms.

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- We showed convergence theorems for the EM and the Gibbs.
- These two algorithms are approximated by simple algorithms. Using this approximation, we can compare different algorithms.
- It may be useful for constructing a new algorithm, or studying efficiency of existing methods.