Imperial College London

HYBRID MARKED POINT PROCESSES

CHARACTERISATION, EXISTENCE AND UNIQUENESS

Maxime Morariu-Patrichi* Joint work with Mikko S. Pakkanen

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^{*}maximemorariu.com

Available quantity



- To buy or sell a stock, traders send orders on their computers to the exchange.
- The limit order book (LOB) is the collection of outstanding orders.
- It evolves with the submission of each order.

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Motivation: marked point processes

- A marked point process (MPP) consists of
 - an increasing sequence of random times $(T_n)_{n \in \mathbb{N}}$ in $(0, \infty]$;
 - a sequence of random marks $(M_n)_{n \in \mathbb{N}}$, where $M_n \in \{1, \ldots, m\}$, say.

$$M_1 = 2 M_2 = 1 M_3 = 1 M_4 = 2$$



Define the counting processes

$$N_i(t):=\sum_{n\in\mathbb{N}}\mathbb{1}(T_n\leq t,M_n=i),\quad t\geq 0,i\in\{1,\ldots,m\}.$$

Approximate definition: the intensity process λ_i(t) of N_i at time t is such that

$$\mathbb{E}\left[N_i(t+dt)-N_i(t)\,|\,\mathcal{F}_t^N\right]\approx\lambda_i(t)dt,$$

where $\mathcal{F}_{t}^{N} := \sigma(N_{i}(s), s \leq t, i = 1, ..., m).$

Motivation: Hawkes processes

A Hawkes process is an MPP that admits intensities such that

$$\lambda_i(t) = \nu_i + \sum_{j=1}^m \int_{[0,t)} k_{ji}(t-s) dN_j(s), \quad t \ge 0, \ i = 1, \dots, m,$$

where $\nu_i > 0$ and $k_{ji} : \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$.

The kernels k_{ij} allow for self- and cross-excitation effects.

- The arrival at time t of an event of type *j* increases the intensity $\lambda_i(t+h)$ of events of type *i* at time t+h by an amount of $k_{ji}(h)$.
- A good candidate for modelling interactions between events (earthquake modelling, criminology, social networks, neurology).
- In LOB models (Large, 2007; Bacry et al., 2016), the marks carry information only on the event type, ignoring the the state of the LOB. However:
 - one might one to keep track of some salient state variables;
 - these state variables might actually influence the arrival intensities of buy and sell orders.

Motivation: Hawkes vs. Markov

- Continuous-time Markov chains: another prominent trend in the LOB modelling literature (Cont et al., 2010; Huang et al., 2015).
 - These models do capture the state of the LOB.
 - But the order flow dynamics can only depend on the state.
 - Interactions like in Hawkes processes are not possible.
- To summarise:
 - Hawkes processes have an event viewpoint.
 - Markov processes have a state viewpoint.
- Our goal is twofold:
 - propose a class of MPPs that allow for an event-state viewpoint;
 - find flexible conditions that ensure the existence and uniqueness of such MPPs.
- Morariu-Patrichi, M. and Pakkanen, M. S. (2017). Hybrid marked point processes: characterisation, existence and uniqueness.
 Preprint, available at: http://arxiv.org/abs/1707.06970.

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- 3 Hybrid marked point processes
- 4 Existence and uniqueness

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Spaces of integer-valued boundedly finite measures

- $\mathcal{M} = \{1, \ldots, m\}$: our mark space (it could be any Polish space).
- *N*[#]_{ℝ≥0×M}: the space of integer-valued boundedly finite measures
 on ℝ_{>0} × *M*. i.e., atomic and finite on all bounded sets.
 - The weak-hash metric d[#] (Daley and Vere-Jones, 2003) makes N[#]_{ℝ>0×M} a complete separable metric space.
 - When *M* is locally compact, this coincides with the vague topology (Kallenberg, 1976).
 - A non-explosive point process (NEPP) is defined as random element in (儿[#]_{ℝ≥0}×𝔄, 𝔅(儿[#]_{ℝ≥0}×𝔄)).
- $\mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#g}$: all the $\xi \in \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#}$ such that $\xi(\{t\} \times \mathscr{M}) = 0$ or 1.
 - $\blacksquare \text{ Hence } \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#g} \subset \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#}.$
 - A non-explosive marked point process (NEMPP) is defined as a random element in $(\mathcal{N}_{\mathbb{R}_{>0}\times\mathcal{M}}^{\#g}, \mathcal{B}(\mathcal{N}_{\mathbb{R}_{>0}\times\mathcal{M}}^{\#g})).$
 - A NEMPP is a MPP $(T_n, M_n)_{n \in \mathbb{N}}$ such that $\lim_{n \to \infty} T_n = \infty$ a.s.

- For all $\xi \in \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#}$ and $t \in \mathbb{R}_{\geq 0}$, define $\xi_t \in \mathcal{N}_{\mathbb{R}_{\leq 0} \times \mathscr{M}}^{\#}$ by
 - $\xi_t(A) := \xi((A + t) \cap [0, t] \times \mathscr{M}), A \in \mathscr{B}(\mathbb{R}_{\leq 0} \times \widetilde{\mathscr{M}}).$
 - ξ_t is the measure ξ stopped at *t* and translated back to the origin.
 - Simply put, ξ_t is the measure ξ viewed from time *t*.



- Similarly, define $\xi_{t-}(\cdot) := \xi((\cdot + t) \cap [0, t) \times \mathscr{M}).$
- - $\mathcal{F}_t^N \subset \mathcal{F}_t$ for all $t \ge 0$.

For all
$$\xi \in \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#}$$
 and $t \in \mathbb{R}_{\geq 0}$, define $\xi_t \in \mathcal{N}_{\mathbb{R}_{<0} \times \mathscr{M}}^{\#}$ by

- $\xi_t(\mathbf{A}) := \xi((\mathbf{A} + t) \cap [\mathbf{0}, t] \times \mathscr{M}), \mathbf{A} \in \mathcal{B}(\mathbb{R}_{\leq \mathbf{0}} \times \widetilde{\mathscr{M}}).$
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- Similarly, define $\xi_{t-}(\cdot) := \xi((\cdot + t) \cap [0, t) \times \mathscr{M}).$
- Given an NEPP *N*, its **internal history** is the filtration $\mathbb{F}^N = (\mathcal{F}_t^N)_{t \in \mathbb{R}_{>0}}$ defined by $\mathcal{F}_t^N := \sigma(N_t)$.
- Given a filtration $\mathbb{F} = (\mathcal{F}_t)_{t \in \mathbb{R}_{\geq 0}}$, we say that *N* is \mathbb{F} -adapted if $\mathcal{F}_t^N \subset \mathcal{F}_t$ for all $t \geq 0$.

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Similarly, define ξ_{t-}(·) := ξ((· + t) ∩ [0, t) × M).
Given an NEPP *N*, its internal history is the filtration 𝔽^N = (𝒯_t^N)_{t∈ℝ≥0} defined by 𝒯_t^N := σ(N_t).
Given a filtration 𝔅 = (𝒯_t)_{t∈ℝ≥0}, we say that *N* is 𝔅-adapted if 𝒯_t^N ⊂ 𝒯_t for all t ≥ 0.

Intensity process and functional

• Let *N* be an \mathbb{F} -adapted NEMPP on $\mathbb{R}_{\geq 0} \times \mathcal{M}$.

- Let $\lambda_i : \Omega \times \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$, $i \in \mathcal{M}$, be a family of \mathbb{F} -predictable processes, that we denote by λ .
- We will use the notation $\lambda(t, m)$ to refer to $\lambda_m(t), t \ge 0, m \in \mathcal{M}$.
- We say that λ is the \mathbb{F} -intensity of N if for every $0 \leq s < t, m \in \mathcal{M}$,

$$\mathbb{E}\left[\mathsf{N}((s,t]\times\{m\})\,|\,\mathcal{F}_{s}\right]=\mathbb{E}\left[\int_{s}^{t}\lambda(u,m)du\,|\,\mathcal{F}_{s}\right].$$

Definition (Intensity functional)

Let $\psi : \mathscr{M} \times \mathcal{N}_{\mathbb{R}_{\leq 0} \times \mathscr{M}}^{\#} \to \mathbb{R}_{\geq 0} \cup \{\infty\}$ be a measurable functional. We furthermore say that N admits ψ as its intensity functional if $\lambda(\omega, t, m) = \psi(m | N_{t-}(\omega))$ holds $\mathbb{P}(d\omega)dt$ -a.e. for all $m \in \mathscr{M}$.

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Mark space and state process

• Let
$$\mathscr{E} = \{1, \ldots, n_{\mathscr{E}}\}, n_{\mathscr{E}} \in \mathbb{N} \text{ and } \mathscr{X} = \{1, \ldots, n_{\mathscr{X}}\}, n_{\mathscr{X}} \in \mathbb{N}.$$

- Each $e \in \mathscr{E}$ is a type of event.
- Each $x \in \mathscr{X}$ is a possible state of a system.
- In the paper, \mathscr{E} and \mathscr{X} can be Polish spaces.
- We consider the mark space $\mathscr{M} := \mathscr{E} \times \mathscr{X}$.
 - Here, \mathcal{M} is still of the form $\{1, \ldots, m\}$ with $m = n_{\mathscr{E}} n_{\mathscr{X}}$.
 - We refer to the elements of *M* using the notation (*e*, *x*), *e* ∈ *E*, *x* ∈ *E*.
- Given an NEMPP on R_{≥0} × *M*, we define the state process X_t at time t as the component x of the most recent mark (e, x) up to time t, exlucluding t.
 - Denote by *F* the functional on $\mathcal{N}^{\#}_{\mathbb{R}_{<0} \times \mathscr{M}}$ such that $X_t = F(N_{t-})$.
 - A mark M_n = (e, x) ∈ ℳ can now be interpreted as an event of type e that moves the system to the state x.
 - If no events occurred up to time *t*, then $X_t = x_0$ for some arbitrary initial condition $x_0 \in \mathcal{X}$.

Example: state-dependent Hawkes process

Let $\phi : \mathscr{X} \times \mathscr{E} \times \mathscr{X} \to \mathbb{R}_{\geq 0}$ be a measurable function such that $\phi(\cdot | e, x)$ is a probability distribution on \mathscr{X} for every $e \in \mathscr{E}, x \in \mathscr{X}$. Consider first a NEMPP *N* with an \mathbb{F}^{N} -intensity λ that satisfies

$$\lambda(t, e, x) = \phi(x \mid e, X_t) \bigg(\nu(e) + \int_0^t \int_{\mathscr{M}} k(t - s, m, e) N(dt, dm) \bigg).$$

"Hawkes part": intensity of events

- If we denote the arrival times and marks of *N* respectively by T_n and $M_n = (E_n, X_n)$, $n \in \mathbb{N}$, then the red term is the \mathbb{F}^N -intensity of the MPP $(T_n, E_n)_{n \in \mathbb{N}}$.
- Events interact like in a Hawkes process but there is also a dependence on the state process.
- "Markov part": transition probabilities of the state process
 - The term φ(x | e, x') is the probability of transitioning from state x' to x when an event of type e occurs.
 - One transition matrix for each possible type of event.

Comparison with Hawkes processes

Why not using instead a Hawkes process on \mathcal{M} with the same interpretation of the marks? Compare the previous intensity to the equation defining a linear Hawkes process:

$$\lambda(t, \boldsymbol{e}, \boldsymbol{x}) = \phi(\boldsymbol{x} \mid \boldsymbol{e}, \boldsymbol{X}_t) \left(\nu(\boldsymbol{e}) + \int_0^t \int_{\mathcal{M}} k(t - \boldsymbol{s}, \boldsymbol{m}, \boldsymbol{e}) N(dt, d\boldsymbol{m}) \right), \quad (1)$$

$$\lambda(t, \boldsymbol{e}, \boldsymbol{x}) = \nu(\boldsymbol{e}, \boldsymbol{x}) + \int_0^t \int_{\mathcal{M}} k(t - \boldsymbol{s}, \boldsymbol{m}, \boldsymbol{e}, \boldsymbol{x}) N(dt, d\boldsymbol{m}).$$

In a Hawkes process, if an event of type e occurs, the probability distribution of the new state depends on the entire history.

But in a LOB, this distribution depends mainly on the current state.

- No such event-state structure with Hawkes processes.
- The intensity in (1) does replicate such a structure however.

Generalisation to hybrid marked point processes

Definition (Hybrid marked point processes)

Let $\eta : \mathscr{E} \times \mathcal{N}_{\mathbb{R} \times \mathscr{M}}^{\#} \to \mathbb{R}_{\geq 0} \cup \{\infty\}$ be a measurable functional. A **hybrid MPP** with transition function ϕ and event functional η is a NEMPP $N : \Omega \to \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#g}$ that admits an \mathbb{F}^{N} -intensity λ such that

 $\lambda(\omega, t, e, x) = \phi(x \mid e, X_t) \eta(e \mid N_{t-}(\omega)), \quad \mathbb{P}(d\omega) dt \text{-} a.e., (e, x) \in \mathcal{M}.$

In other words, N admits ψ as its intensity functional, where

 $\psi(m \mid \xi) := \phi(x \mid e, F(\xi)) \eta(e \mid \xi), \quad m = (e, x) \in \mathcal{M}, \xi \in \mathcal{N}_{\mathbb{R}_{\leq 0} \times \mathcal{M}}^{\#}.$

Implied dynamics and characterisation

Theorem (Implied dynamics and characterisation)

Suppose that N is a NNEMP on $\mathbb{R}_{\geq 0} \times \mathscr{M}$ with an \mathbb{F}^{N} -intensity. Then, N is a hybrid MPP with transition function ϕ and event functional η if and only if the following two statements hold.

- 1 $N_{\mathscr{E}}(\cdot) := N(\cdot \times \mathscr{X})$ is a NEMPP on $\mathbb{R}_{\geq 0} \times \mathscr{E}$ that admits an \mathbb{F}^{N} -intensity $\lambda_{\mathscr{E}}$ such that $\lambda_{\mathscr{E}}(t, e) = \eta(e \mid N_{t-})$.
- 2 Let $t \in \mathbb{R}_{\geq 0}$ and denote by τ the first event time after time t and by M = (E, X) the corresponding mark. We have that

$$\mathbb{P}\left(X=x\,|\,\sigma(E)\vee\mathcal{F}_{\tau-}^{N}\right)\mathbb{1}_{\{\tau<\infty\}}=\phi(x\,|\,E,X_{t})\mathbb{1}_{\{\tau<\infty\}},\quad a.s.$$

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The existence and uniqueness problem

- Self-referential nature of the definition of a hybrid MPP: it is not clear that such a NEMPP exists.
- More generally, given a functional ψ, one can ask if there exists a NEMPP on ℝ_{≥0} × ℋ that admits ψ as its intensity functional.
- Massoulié (1998) tackles this question by reformulating the existence problem as a Poisson-driven SDE.
 - Strong existence and uniqueness is obtained by imposing the Lipschitz condition

$$|\psi(m|\xi) - \psi(m|\xi')| \leq \iint_{\mathbb{R}_{<0} \times \mathscr{M}} \overline{k}(-t',m',m)|\xi - \xi'|(dt',dm'),$$

where $m \in \mathcal{M}$, $\xi, \xi' \in \mathcal{N}_{\mathbb{R}_{>0} \times \mathcal{M}}^{\#}$.

- This can be applied to Hawkes processes.
- But this condition is not satisfied by state-dependent Hawkes processes for example.
- Our goal: find a weaker condition that ensures strong existence and uniqueness.

The Poisson-driven SDE

• Let $(\Omega, \mathcal{F}, \mathbb{P})$ be given and complete.

• Let $M : \Omega \to \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M} \times \mathbb{R}_{\geq 0}}^{\#}$ be a Poisson PP on $\mathbb{R}_{\geq 0} \times \mathscr{M} \times \mathbb{R}_{\geq 0}$:

- M(A₁),..., M(A_n) are mutually independent for disjoint and bounded sets A₁,..., A_n ∈ B(ℝ_{≥0} × M × ℝ_{≥0});
- $M(A \times \{m\} \times B)$ follows a Poisson distribution with parameter Leb(A)Leb(B), where $A, B \in \mathcal{B}(\mathbb{R}_{\geq 0})$.
- Let \mathbb{F} be the completion of the natural filtration \mathbb{F}^{M} .

Definition (The Poisson-driven SDE)

By a solution to the Poisson-driven SDE, we mean an \mathbb{F} -adapted NEMPP $N:\Omega\to\mathcal{N}_{\mathbb{R}_{>0}\times\mathscr{M}}^{\#g}$ that solves

$$\begin{cases} \mathsf{N}(dt, dm) = \mathsf{M}(dt, dm, (0, \lambda(t, m)]), & t \in \mathbb{R}_{\geq 0}, \text{ a.s.}, \\ \lambda(t, m) = \psi(m | \theta_t N^{< 0}), & t \in \mathbb{R}_{\geq 0}, m \in \mathscr{M}, \omega \in \Omega. \end{cases}$$

Intuition: visualising the equation

- Take the simplest case when $\mathcal{M} = \{1\}$, i.e., no marks.
- For example, consider the intensity functional $\psi(\xi) = 1 + \int_{(-\infty,0)} e^{2t} \xi(dt)$, i.e., a Hawkes process.



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 For example, consider the intensity functional ψ(ξ) = 1 + ∫_(-∞,0) e^{2t}ξ(dt), i.e., a Hawkes process.



- Thanks to the discrete nature of *M*, at each event time, we know the intensity process until the next event time.
- For each $\omega \in \Omega$, it looks we can construct an increasing sequence $(T_n(\omega))_{n \in \mathbb{N}}$ such that $N(\omega) := \sum_{n \in \mathbb{N}} \delta_{T_1(\omega)} \mathbb{1}_{T_n(\omega) < \infty}$ is a solution.



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Pathwise construction: how to be rigorous

To prove strong existence, we follow these steps.

- Write down formally this algorithm and prove that it is well-defined.
- Check that the constructed N solves the SDE up to each T_n.
- Show that each T_n is an \mathbb{F} -stopping time and that each "piece" of λ is \mathbb{F} -predictable.
- Dominate *N* by a NEPP \overline{N} to show that $\lim_{n\to\infty} T_n = \infty$ a.s.
- Prove that $N \in \mathcal{N}_{\mathbb{R}_{>0}}^{\#g}$ a.s., i.e., $N(\{t\}) = 0$ or 1.
- Use a Poisson embedding lemma to conclude that a version of N is NEMPP that solves the Poisson-driven SDE and admits ψ as its intensity functional.

Assumptions

To follow these steps in the general case, we need some assumptions.

- \blacksquare The mark space \mathscr{M} is bounded.
- There exists $\lambda_0 \in \mathbb{R}_{\geq 0}$ and a bounded measurable function $\overline{k} : \mathbb{R}_{>0} \times \mathscr{M} \times \mathscr{M} \to \mathbb{R}_{\geq 0}$ such that

$$\psi(m \mid \xi) \leq \lambda_0 + \iint_{(-\infty,0) \times \mathscr{M}} \overline{k}(-t', m', m)\xi(dt', dm') =: \overline{\psi}(m \mid \xi).$$

• We dominate *N* by a Hawkes process with intensity functional $\overline{\psi}$.

- The kernel \overline{k} satisfies $\sup_{m \in \mathscr{M}} \sum_{m' \in \mathscr{M}} \int_{(0,\infty)} \overline{k}(t',m',m) dt' < 1$.
 - This allows us to apply the results of Massoulié (1998) to $\overline{\psi}$.
- In the paper, we allow for a general initial condition on $(-\infty, 0]$.
 - Extra assumptions on the initial condition are required.

Remark. Here, there are no events before t = 0 and, thus, we could relax the above assumptions.

Existence and uniqueness

Theorem (Strong existence)

Under the previous assumptions, there exists a NEMPP $N: \Omega \to \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#g}$ that solves the Poisson-driven SDE. Any such N admits ψ as its intensity functional.

Since we restrict ourselves to NEMPPs, we can prove strong uniqueness without any specific assumptions.

Theorem (Strong uniqueness)

Let $N : \Omega \to \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#g}$ and $N' : \Omega \to \mathcal{N}_{\mathbb{R}_{\geq 0} \times \mathscr{M}}^{\#g}$ be two NEMPPs solving the Poisson-Driven SDE. Then N = N' a.s.

Remark. By applying Theorem 3.4 in Jacod (1975), we also obtain weak uniqueness.

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Conclusion: transporting the idea to ambit fields?

- The set $\{(t, m, z) \in \mathbb{R}_{\geq 0} \times \mathscr{M} \times \mathbb{R}_{\geq 0} : z \leq \lambda(t, m)\}$ can be interpreted as the "ambit set" of the process.
- This set **expands** randomly depending on the process.
- In ambit fields however, the ambit set is fixed and **translated**.
- Idea: combine both to obtain endogenous intermittency?



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